PM300RSE060

FEATURE
a) Adopting new 4th generation planar IGBT chip, which performance is improved by 1µm fine rule process. For example, typical VCE(sat)=1.7V
b) Using new Diode which is designed to get soft reverse recovery characteristics.
   • 3φ 300A, 600V Current-sense IGBT for 15kHz switching
   • 100A, 600V Current-sense regenerative brake IGBT
   • Monolithic gate drive & protection logic
   • Detection, protection & status indication circuits for over-current, short-circuit, over-temperature & under-voltage
   • Acoustic noise-less 30kW class inverter application

APPLICATION
General purpose inverter, servo drives and other motor controls

PACKAGE OUTLINES Dimensions in mm
INTERNAL FUNCTIONS BLOCK DIAGRAM

MAXIMUM RATINGS (Tj = 25°C, unless otherwise noted)

**INVERTER PART**

<table>
<thead>
<tr>
<th>Symbol</th>
<th>Parameter</th>
<th>Condition</th>
<th>Ratings</th>
<th>Unit</th>
</tr>
</thead>
<tbody>
<tr>
<td>VCES</td>
<td>Collector-Emitter Voltage</td>
<td>VD = 15V, VCIN = 15V</td>
<td>600</td>
<td>V</td>
</tr>
<tr>
<td>±IC</td>
<td>Collector Current</td>
<td>TC = 25°C</td>
<td>300</td>
<td>A</td>
</tr>
<tr>
<td>±ICP</td>
<td>Collector Current (Peak)</td>
<td>TC = 25°C</td>
<td>600</td>
<td>A</td>
</tr>
<tr>
<td>PC</td>
<td>Collector Dissipation</td>
<td>TC = 25°C</td>
<td>781</td>
<td>W</td>
</tr>
<tr>
<td>Tj</td>
<td>Junction Temperature</td>
<td></td>
<td>−20 ~ +150</td>
<td>°C</td>
</tr>
</tbody>
</table>

**BRAKE PART**

<table>
<thead>
<tr>
<th>Symbol</th>
<th>Parameter</th>
<th>Condition</th>
<th>Ratings</th>
<th>Unit</th>
</tr>
</thead>
<tbody>
<tr>
<td>VCES</td>
<td>Collector-Emitter Voltage</td>
<td>VD = 15V, VCIN = 15V</td>
<td>600</td>
<td>V</td>
</tr>
<tr>
<td>IC</td>
<td>Collector Current</td>
<td>TC = 25°C</td>
<td>100</td>
<td>A</td>
</tr>
<tr>
<td>ICP</td>
<td>Collector Current (Peak)</td>
<td>TC = 25°C</td>
<td>200</td>
<td>A</td>
</tr>
<tr>
<td>PC</td>
<td>Collector Dissipation</td>
<td>TC = 25°C</td>
<td>416</td>
<td>W</td>
</tr>
<tr>
<td>Vr(DC)</td>
<td>FWDi Rated DC Reverse Voltage</td>
<td>TC = 25°C</td>
<td>600</td>
<td>V</td>
</tr>
<tr>
<td>IF</td>
<td>FWDi Forward Current</td>
<td>TC = 25°C</td>
<td>100</td>
<td>A</td>
</tr>
<tr>
<td>Tj</td>
<td>Junction Temperature</td>
<td></td>
<td>−20 ~ +150</td>
<td>°C</td>
</tr>
</tbody>
</table>

**CONTROL PART**

<table>
<thead>
<tr>
<th>Symbol</th>
<th>Parameter</th>
<th>Condition</th>
<th>Ratings</th>
<th>Unit</th>
</tr>
</thead>
<tbody>
<tr>
<td>Vd</td>
<td>Supply Voltage</td>
<td>Applied between : VUp1-VUpC, VVP1-VVPc, VWp1-VWPC, VN1-VNC</td>
<td>20</td>
<td>V</td>
</tr>
<tr>
<td>Vin</td>
<td>Input Voltage</td>
<td>Applied between : Up-VUpC, Vp-VVPc, Wp-VWPC, Un • Vn • Wn • Br-VNC</td>
<td>20</td>
<td>V</td>
</tr>
<tr>
<td>Vfo</td>
<td>Fault Output Supply Voltage</td>
<td>Applied between : Fo-Vnc</td>
<td>20</td>
<td>V</td>
</tr>
<tr>
<td>Ifd</td>
<td>Fault Output Current</td>
<td>Sink current at Fo terminal</td>
<td>20</td>
<td>mA</td>
</tr>
</tbody>
</table>
**TOTAL SYSTEM**

<table>
<thead>
<tr>
<th>Symbol</th>
<th>Parameter</th>
<th>Condition</th>
<th>Ratings</th>
<th>Unit</th>
</tr>
</thead>
<tbody>
<tr>
<td>$V_{CC(PRT)}$</td>
<td>Supply Voltage Protected by OC &amp; SC</td>
<td>$V_D = 13.5 \sim 16.5,V$, Inverter Part, $T_j = 125^\circ,C$ Start</td>
<td>400</td>
<td>V</td>
</tr>
<tr>
<td>$V_{CC(surge)}$</td>
<td>Supply Voltage (Surge)</td>
<td>Applied between : P-N, Surge value or without switching</td>
<td>500</td>
<td>V</td>
</tr>
<tr>
<td>$T_c$</td>
<td>Module Case Operating Temperature</td>
<td>(Note-1)</td>
<td>$-20 \sim +100$</td>
<td>°C</td>
</tr>
<tr>
<td>$T_{stg}$</td>
<td>Storage Temperature</td>
<td></td>
<td>$-40 \sim +125$</td>
<td>°C</td>
</tr>
<tr>
<td>$V_{iso}$</td>
<td>Isolation Voltage</td>
<td>60Hz, Sinusoidal, Charged part to Base, AC 1 min.</td>
<td>2500</td>
<td>V rms</td>
</tr>
</tbody>
</table>

(Note-1) $T_c$ measurement point is as shown below. (Base plate depth 3mm)

![Tc measurement point diagram](image)

**THERMAL RESISTANCES**

<table>
<thead>
<tr>
<th>Symbol</th>
<th>Parameter</th>
<th>Test Condition</th>
<th>Limits</th>
<th>Unit</th>
</tr>
</thead>
<tbody>
<tr>
<td>$R_{th(j-c)}$</td>
<td>Junction to case Thermal Resistances</td>
<td>Inverter IGBT part (per 1 element), (Note-1)</td>
<td>— — 0.16</td>
<td>°C/W</td>
</tr>
<tr>
<td>$R_{th(f-a)}$</td>
<td></td>
<td>Inverter FWDi part (per 1 element), (Note-1)</td>
<td>— — 0.24</td>
<td>°C/W</td>
</tr>
<tr>
<td>$R_{th(j-c)}$</td>
<td></td>
<td>Brake IGBT part, (Note-1)</td>
<td>— — 0.30</td>
<td>°C/W</td>
</tr>
<tr>
<td>$R_{th(f-a)}$</td>
<td></td>
<td>Brake FWDi part, (Note-1)</td>
<td>— — 0.80</td>
<td>°C/W</td>
</tr>
<tr>
<td>$R_{th(j-c)}$</td>
<td></td>
<td>Inverter IGBT part (per 1 element), (Note-2)</td>
<td>— — 0.10</td>
<td>°C/W</td>
</tr>
<tr>
<td>$R_{th(f-a)}$</td>
<td></td>
<td>Brake FWDi part (per 1 element), (Note-2)</td>
<td>— — 0.16</td>
<td>°C/W</td>
</tr>
<tr>
<td>$R_{th(c-f)}$</td>
<td>Contact Thermal Resistance</td>
<td>Case to fin, Thermal grease applied (per 1 module)</td>
<td>— — 0.018</td>
<td>°C/W</td>
</tr>
</tbody>
</table>

(Note-2) $T_c$ measurement point is just under the chips.

If you use this value, $R_{th(f-a)}$ should be measured just under the chips.

**ELECTRICAL CHARACTERISTICS** ($T_j = 25^\circ\,C$, unless otherwise noted)

**INVERTER PART**

<table>
<thead>
<tr>
<th>Symbol</th>
<th>Parameter</th>
<th>Test Condition</th>
<th>Limits</th>
<th>Unit</th>
</tr>
</thead>
<tbody>
<tr>
<td>$V_{CE(sat)}$</td>
<td>Collector-Emitter Saturation Voltage</td>
<td>$V_D = 15V$, $I_C = 300A$, $V_{CIN} = 0V$, Pulsed</td>
<td>$T_j = 25^\circ,C$</td>
<td>0.4 — 1.7</td>
</tr>
<tr>
<td>$V_{CE}$</td>
<td>FWDi Forward Voltage</td>
<td>$-I_C = 300A, V_D = 15V$, $V_{CIN} = 15V$</td>
<td>$T_j = 125^\circ,C$</td>
<td>2.2 — 3.3</td>
</tr>
<tr>
<td>$I_{on}$</td>
<td>Switching Time</td>
<td>$V_D = 15V$, $V_{CIN} = 15V+10V$</td>
<td></td>
<td>0.4 — 0.15</td>
</tr>
<tr>
<td>$I_{off}$</td>
<td></td>
<td>$V_{CCE} = 300V$, $I_C = 300A$</td>
<td></td>
<td>0.4 — 0.10</td>
</tr>
<tr>
<td>$t_{on}$</td>
<td></td>
<td>$T_j = 125^\circ,C$</td>
<td></td>
<td>2.0 — 2.9</td>
</tr>
<tr>
<td>$t_{off}$</td>
<td>Inductive Load (upper and lower arm)</td>
<td></td>
<td></td>
<td>0.6 — 1.2</td>
</tr>
<tr>
<td>$I_{CES}$</td>
<td>Collector-Emitter Cutoff Current</td>
<td>$V_{CE} = V_{CES}$, $V_{CIN} = 15V$</td>
<td>$T_j = 25^\circ,C$</td>
<td>— — 1</td>
</tr>
<tr>
<td></td>
<td></td>
<td>$T_j = 125^\circ,C$</td>
<td></td>
<td>— — 10</td>
</tr>
</tbody>
</table>
## BRAKE PART

<table>
<thead>
<tr>
<th>Symbol</th>
<th>Parameter</th>
<th>Test Condition</th>
<th>Limits</th>
<th>Unit</th>
</tr>
</thead>
<tbody>
<tr>
<td>VCEsat</td>
<td>Collector-Emitter Saturation Voltage</td>
<td>VD = 15V, IC = 100A, VCE = VCES, VCI = 15V</td>
<td>—</td>
<td>2.35</td>
</tr>
<tr>
<td>VFM</td>
<td>Forward Voltage</td>
<td>IF = 100A (Fig. 2)</td>
<td>—</td>
<td>2.2</td>
</tr>
<tr>
<td>ICES</td>
<td>Collector-Emitter Cutoff Voltage</td>
<td>VCE = VCES, VCI = 15V (Fig. 4)</td>
<td>—</td>
<td>—</td>
</tr>
</tbody>
</table>

## CONTROL PART

<table>
<thead>
<tr>
<th>Symbol</th>
<th>Parameter</th>
<th>Test Condition</th>
<th>Limits</th>
<th>Unit</th>
</tr>
</thead>
<tbody>
<tr>
<td>Id</td>
<td>Circuit Current</td>
<td>VD = 15V, VCI = 15V</td>
<td>VN1-VN1</td>
<td>52</td>
</tr>
<tr>
<td>Vth(ON)</td>
<td>Input ON Threshold Voltage</td>
<td>Applied between : UP-UPC, VP-VPPC, WP-WPC</td>
<td>Un, VN, WN, Br-VNC</td>
<td>1.2</td>
</tr>
<tr>
<td>Vth(OFF)</td>
<td>Input OFF Threshold Voltage</td>
<td>Inverter part</td>
<td>VN1-VNC</td>
<td>1.7</td>
</tr>
</tbody>
</table>

## MECHANICAL RATINGS AND CHARACTERISTICS

<table>
<thead>
<tr>
<th>Symbol</th>
<th>Parameter</th>
<th>Test Condition</th>
<th>Limits</th>
<th>Unit</th>
</tr>
</thead>
<tbody>
<tr>
<td>—</td>
<td>Mounting torque</td>
<td>Main terminal</td>
<td>Screw : M5</td>
<td>2.5</td>
</tr>
<tr>
<td>—</td>
<td>Mounting torque</td>
<td>Mounting part</td>
<td>Screw : M5</td>
<td>2.5</td>
</tr>
<tr>
<td>—</td>
<td>Weight</td>
<td>—</td>
<td>—</td>
<td>920</td>
</tr>
</tbody>
</table>

## RECOMMENDED CONDITIONS FOR USE

<table>
<thead>
<tr>
<th>Symbol</th>
<th>Parameter</th>
<th>Test Condition</th>
<th>Recommended value</th>
<th>Unit</th>
</tr>
</thead>
<tbody>
<tr>
<td>VCC</td>
<td>Supply Voltage</td>
<td>Applied across P-N terminals</td>
<td>≤ 400</td>
<td>V</td>
</tr>
<tr>
<td>Vd</td>
<td>Control Supply Voltage</td>
<td>Applied between : UP-UPC, VP-VP, WP-WPC</td>
<td>15 ± 1.5</td>
<td>V</td>
</tr>
<tr>
<td>VCM(ON)</td>
<td>Input ON Voltage</td>
<td>Applied between : UP-UPC, VP-VP, WP-WPC</td>
<td>≤ 0.8</td>
<td>V</td>
</tr>
<tr>
<td>VCM(OFF)</td>
<td>Input OFF Voltage</td>
<td>VUP1-VUPC, VP1-VP, WP1-WP, VN1-VN, Br-VN</td>
<td>≥ 4.0</td>
<td>V</td>
</tr>
<tr>
<td>fPWM</td>
<td>PWM Input Frequency</td>
<td>Using Application Circuit input signal of IPM, 3φ sinusoidal PWM VVVF inverter (Fig. 8)</td>
<td>≤ 20</td>
<td>kHz</td>
</tr>
<tr>
<td>tdead</td>
<td>Arm Shoot-through Blocking Time</td>
<td>For IPM’s each input signals (Fig. 7)</td>
<td>≥ 2.5</td>
<td>µs</td>
</tr>
</tbody>
</table>

(Note-4) Allowable Ripple rating of Control Voltage : dv/dt ≤ ±5V/µs, 2Vp-p
PRECAUTIONS FOR TESTING

1. Before applying any control supply voltage (Vd), the input terminals should be pulled up by resistors, etc. to their corresponding supply voltage and each input signal should be kept off state.

After this, the specified ON and OFF level setting for each input signal should be done.

2. When performing “OC” and “SC” tests, the turn-off surge voltage spike at the corresponding protection operation should not be allowed to rise above VCES rating of the device.

(These test should not be done by using a curve tracer or its equivalent.)

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**Fig. 1** Vce(sat) Test

**Fig. 2** Vcc, (Vsw) Test

**Fig. 3** Switching time Test circuit and waveform

**Fig. 4** Ices Test

**Fig. 5** OC and SC Test

**Fig. 6** OC and SC Test waveform

**Fig. 7** Dead time measurement point example
NOTES FOR STABLE AND SAFE OPERATION:

- Design the PCB pattern to minimize wiring length between opto-coupler and IPM's input terminal, and also to minimize the stray capacity between the input and output wirings of opto-coupler.
- Quick opto-couplers: TPLH, TPLH ≤ 0.8μs. Use High CMR type. The line between opto-coupler and intelligent module should be shortened as much as possible to minimize the floating capacitance.
- Slow switching opto-coupler: recommend to use at CTR = 100 ~ 200%, Input current = 8 ~ 10mA, to work in active.
- Use 4 isolated control power supplies (VD). Also, care should be taken to minimize the instantaneous voltage charge of the power supply.
- Make inductance of DC bus line as small as possible, and minimize surge voltage using snubber capacitor between P and N terminal.
- Use line noise filter capacitor (ex. 4.7nF) between each input AC line and ground to reject common-mode noise from AC line and improve noise immunity of the system.

Fig. 8 Application Example Circuit